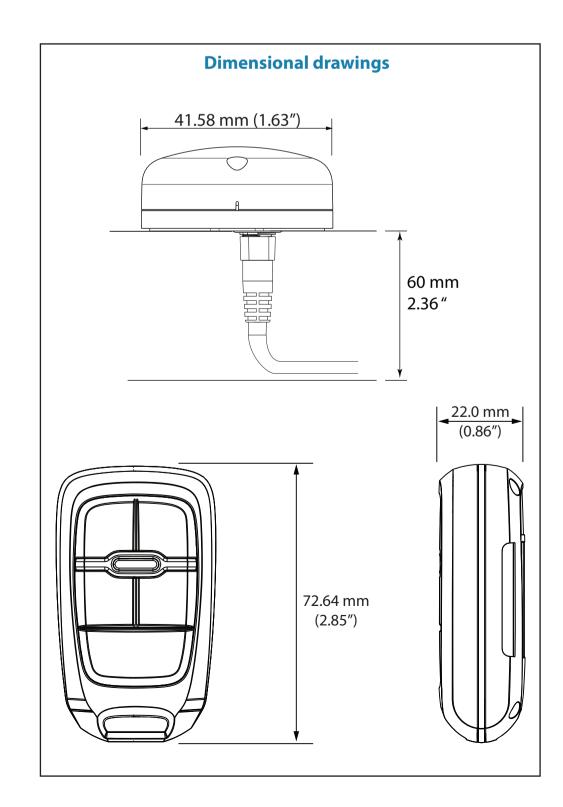


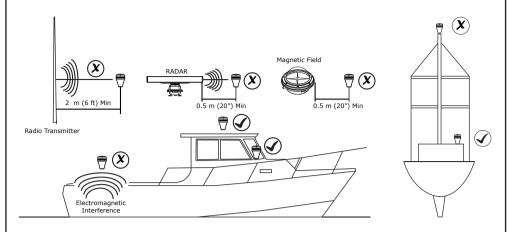


| Specifications | | | | |
|----------------------------|--|--|--|--|
| Base station | | | | |
| Dimensions | Ø 90 mm, H 38 mm (Ø 3.54" H 1.50") | | | |
| Power supply and interface | 9-16 V DC via Micro-C network | | | |
| Power consumption | <100 mA at 12 V DC | | | |
| Temperature | Operating: -25°C to +60°C, Storage: -40°C to +85°C | | | |
| Humidity | 66°C, 95% RH, 18 hrs | | | |
| Environmental protection | IPx7 | | | |
| In-rush current | 2 A for 20 ms (@ internal 5 V) | | | |
| Connection cable: | Micro-C drop cable 1.8 m (6 ft) | | | |
| Signal wire gauge | 24 AWG | | | |
| Power wire gauge | 22 AWG | | | |
| Power wire resistance | 5.7 ohms per 100 meters | | | |
| Maximum current | 3 A | | | |
| Connector | Micro-C T-Joiner | | | |
| Remote controller | | | | |
| Dimensions | H 72.64 mm, W 41.58 mm, D 22 mm, Weight: | | | |
| Power supply | 2 AAA batteries | | | |
| Temperature | Operating: -20°C to +55°C, Storage: -30°C to +70°C | | | |
| Humidity | 66℃, 95% RH, 18 hrs | | | |
| Environmental protection | IPx6, IPx7 | | | |
| Operation | 5 buttons | | | |
| Communication | Bluetooth via Base station, range >30 m | | | |
| Mounting | Lanyard strap or wrist mounted | | | |
| | | | | |
| Brand | Supported autopilot systems | | | |
| Simrad | NAC-1, AC12, AC42, SG05 | | | |
| Simrad Pro | AC70 | | | |
| Lowrance | Outboard Pilot | | | |



Mounting location of base station

- Avoid installing the base station behind other electrical and electronic devices, as they may interfere with the signal and consistency of wireless communication.
- The base station should be at least 2 meters away from any other Bluetooth or wireless LAN (WiFi) transceiver.
- It is advisable to check Bluetooth connection throughout the boat by pairing the unit before permanently mounting the base station.



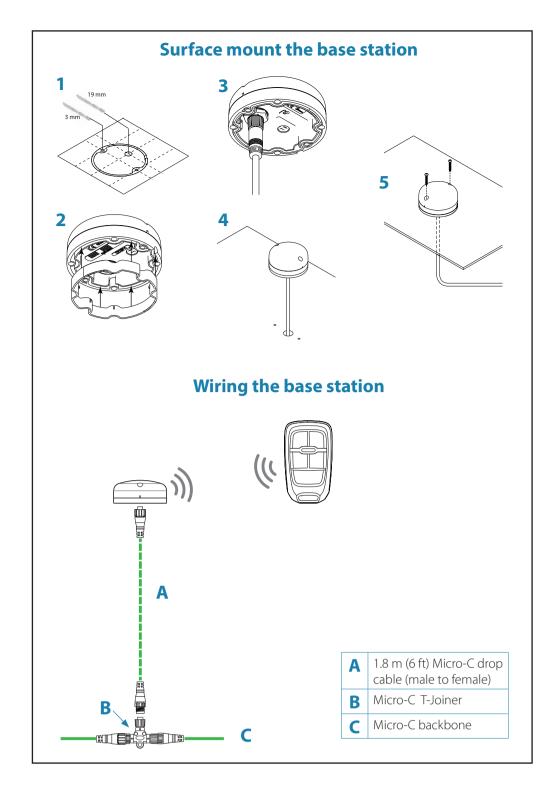
Pairing a remote to the base station

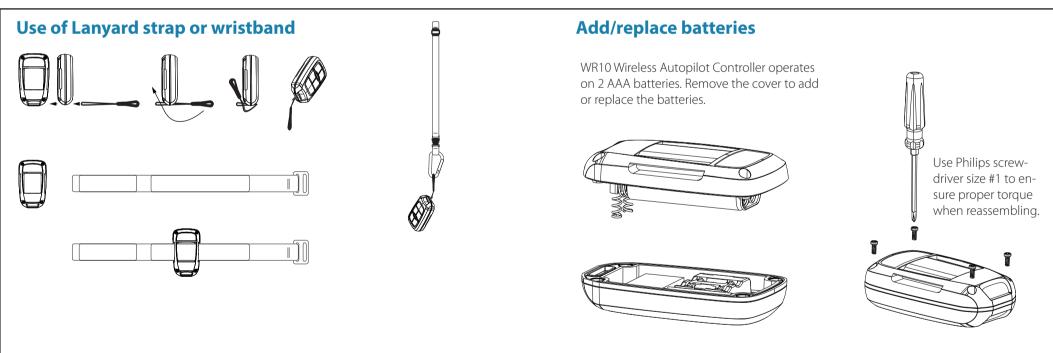
First, make sure that:

- the batteries in the remote are not low.
- the remote and the base station are placed as close together as possible.
- the AP system is OFF or in standby.

Then continue to:

- 1. Remove power from the base station.
- 2. Press and hold the buttons MODE and STBY on the remote for at least 5 seconds until a single quick green LED flashes. The remote is now in Discoverable mode and will stay in this mode for 60 seconds or until base station asks to pair.
- **3.** Power up base station. For the first 10 seconds, the base station will search for Discoverable remotes.
- **4.** Wait till remote quickly flashes the green LED every second, indicating that the base station is asking to pair.
- **5.** Press the AUTO button for at least 1 second to start the pairing.
 - When successfully paired: The green LED will stay on for 2 seconds.
 - When pairing failed: The red LED will stay on for 2 seconds.





Operation

| Keys and LED | Action Mode: | Auto | Standby | Wind | NoDrift |
|---|---|-----------|---------|-----------|-----------|
| < Left arrow Port or > Right arrow Starboard | Short press: Adjust 1° to Port/Starboard i.e. heading in Auto mode, course in NoDrift mode and wind angle in Wind mode. | $\sqrt{}$ | | $\sqrt{}$ | $\sqrt{}$ |
| | Long press (2s): Adjust 10° to Port/Starboard i.e. heading in Auto mode, course in NoDrift mode and wind angle in Wind mode. | V | | $\sqrt{}$ | $\sqrt{}$ |
| < Left arrow + > Right arrow | Autotack (in Wind mode), press and hold until LED is flashing green rapidly, then press AUTO to confirm. | | | $\sqrt{}$ | |
| STBY | Place the autopilot into Standby mode. | √ | | $\sqrt{}$ | √ |
| MODE | Changes the autopilot mode: | | | | |
| | 1. Boats set to SAIL: Toggles AUTO and WIND modes. | √ | | $\sqrt{}$ | |
| | 2. Other boat types: Toggles AUTO and NoDrift modes. | √ | | | √ |
| AUTO | Engages the autopilot into AUTO mode. | | √ | $\sqrt{}$ | √ |
| LED* | Green for 1s indicates message acknowledged. Red for 1s indicates message is either rejected or not acknowledged. | √ | √ | $\sqrt{}$ | √ |
| | Green rapid flashes for up to 10s, followed by solid green for 1s. Red for 1s indicates message is either rejected or not acknowledged. | | | $\sqrt{}$ | |

* Note: In addition to the LED behaviour specified: Red will flash for 1s every 10s when battery level is low.